

Analytical calculations of the solid angle subtended by a circular detector at linear sources

Mahmoud I. Abbas

Abstract: Knowledge of the geometrical solid angle is essential in all absolute measurements of the strengths of radioactive materials and to calibrate detectors. A direct mathematical formalism for the determination of the geometrical solid angle and the geometrical efficiency of a circular detector and an arbitrarily positioned line source is deduced. The results have been compared with previous computational treatments. The comparison shows a very satisfactory agreement in all cases.

Keywords: Geometrical solid angle; Geometrical efficiency; Linear sources; Circular detector.

1 Introduction

The geometrical solid angle Ω is widely used during absolute methods to calibrate detectors or to determine the activity of a radioactive source. This parameter describes the angular extent of particle or ray emitted by a point source and collected by the detector system. The ideal detector would surround an isotropically radiating point source and has a geometrical solid angle of 4π steradians. Due to the practical limitations of sample shape and instrumentation access, as well as the physical geometry of the detector reaching this level of geometrical efficiency (i.e., $4\pi = 100\%$), is unrealizable. Nevertheless, the specification and use of geometrical solid angle as a qualifying parameter which can be used to calculate the benefits of a detector configuration, rather than its physical size, is an important distinction. This is most important when assessing various geometries as physically larger detectors do not always correlate with greater geometrical solid angles and thus more efficient and statistically significant data collection or greater sensitivity capabilities. Conway (2010) has been reported recently [1], the treatments of the geometrical solid angle subtended by a circular detector at line source. He used a new axisymmetric radiation vector potential method

Manuscript received November 11, 2018; accepted May 25, 2018.

Mahmoud I. Abbas is with the Physics Department, Faculty of Science, Alexandria University, 21511 Alexandria, Egypt

to solve the geometrical efficiency of a line source and a circular disk detector when the line source is parallel to the detector axis. Recently, Selim and Abbas [2–15] calculated the geometrical, total and full-energy peak efficiencies for any source-detector configuration using spherical coordinates system. In this paper using the previous approach, we present a direct mathematical method to calculate the geometrical solid angle subtended by a cylindrical detector at arbitrarily positioned line sources. The arrangement of this paper is as follows. Section 2 presents direct mathematical formulae for the geometrical solid angle, and consequently the geometrical efficiency ($\epsilon_g = \Omega/4\pi$), in the case of an arbitrarily positioned line source. Section 3 contains the validation of the present method. Conclusions are presented in Section 4.

2 Mathematical viewpoint

In the present work we derive a statistical integral formulation for the geometrical solid angle subtended by a circular detector of radius R at an arbitrarily positioned isotropic radiating point source, with lateral distance ρ , by using a spherical coordinate technique. The geometrical solid angle is given by [2]:

$$\Omega = 2\pi - \int_0^{2\pi} g(\rho, \xi, h) d\xi \quad (1)$$

where,

$$g(\rho, \xi, h) = \frac{h(h^2 + \rho^2 + R\rho \sin\xi)}{(h^2 + \rho^2 \cos^2\xi)(h^2 + R^2 + \rho^2 + 2R\rho \sin\xi)^{\frac{1}{2}}} \quad (2)$$

The geometrical notations of h, R and ρ are as shown in Fig. 1.

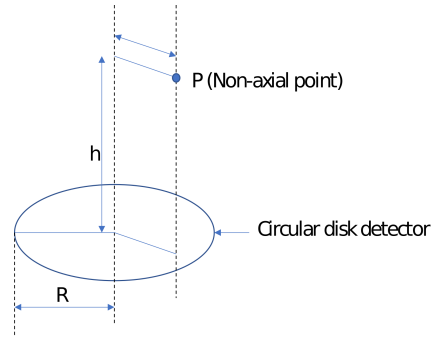


Fig. 1.

The work described below involves the use of direct analytical formulae for the computation of the geometrical solid angle subtended by a circular detector at linear sources assumed to be located along and parallel to its axis.

2.1 Line source assumed to be located along the axis of a circular detector

The geometrical solid angle subtended by a circular detector of radius R and a line source assumed to be located along the axis of a circular detector is shown in Fig 2, is given by:

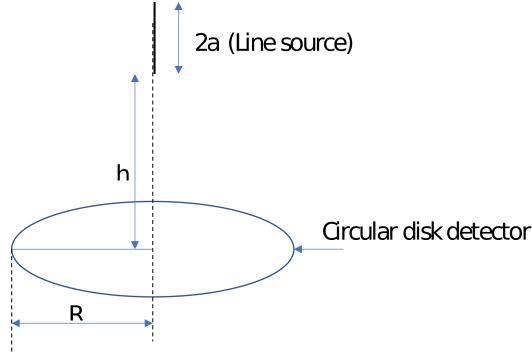


Fig. 2.

$$\Omega = \frac{1}{2a} \int_{h-a}^{h+a} (2\pi - \int_0^{2\pi} g(0, \xi, h) d\xi) dh \quad (3)$$

$$\varepsilon_g = \frac{\Omega}{4\pi} \quad (4)$$

$$\varepsilon_g = \frac{1}{4\pi \cdot 2a} \int_{h-a}^{h+a} (2\pi - \int_0^{2\pi} g(0, \xi, h) d\xi) dh \quad (5)$$

$$\varepsilon_g = \frac{1}{4a} \int_{h-a}^{h+a} \left(1 - \frac{h}{\sqrt{h^2 + R^2}}\right) dh \quad (6)$$

where, $g(\rho, \xi, h)$ is as identified before in equation (2).

2.2 Line source assumed to be located parallel to the axis of a circular detector

The geometrical solid angle subtended by a circular detector of radius R and a line source assumed to be located parallel to the axis of a circular detector is shown in Fig 3.

$$\varepsilon_g = \frac{1}{4\pi \cdot 2a} \int_{h-a}^{h+a} (2\pi - \int_0^{2\pi} g(\rho, \xi, h) d\xi) dh \quad (7)$$

where, $g(\rho, \xi, h)$ is as identified before in equation (2). Setting the lateral distance $\rho = 0$ in the previous equations, we obtain the geometrical efficiency of a circular detector (with radius R) and a line source assumed to be located along the axis of a circular detector (equation 6).

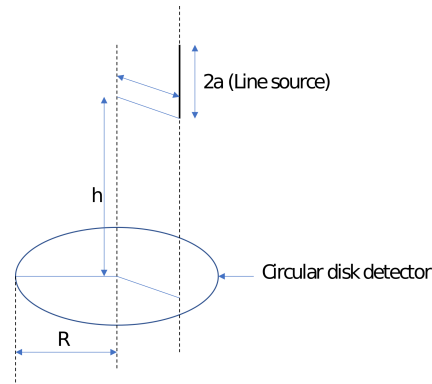


Fig. 3.

3 Validation of the present method

Systematic calculations of the geometrical efficiency of a circular detector of radius R and a line source located along and parallel to the axis of a circular detector is were calculated and tabulated in tables 1 and 2, respectively. The percentage deviations between calculated efficiency values (using the present formulae and that published by Conway, 2010 [1]) are less than ($10^{-10}\%$). The percentage deviation is given by:

$$\Delta\% = \frac{\mathcal{E}_{\text{presentwork}} - \mathcal{E}_{\text{Conway}}}{\mathcal{E}_{\text{presentwork}}} \times 100\% \quad (8)$$

Table 1. Geometrical efficiency \mathcal{E}_g for a circular detector of radius R and a linear source of length $2a$. The source lies along the detector axis with its center at a distance h from the detector. Distances are in arbitrary units

R	h	a	Geometrical efficiency (\mathcal{E}_g)	
			Conway [2]	Present work
10	5	3	0.282649212693323	0.282649212693323
10	5	5	0.292893218813452	0.292893218813452
10^5	5	5	0.499975000000062	0.499975000000062
10	1	1	0.450490243203608	0.450490243203608
10	0.1	0.1	0.495000499900025	0.495000499900025
10	10	2	0.148218640381549	0.148218640381549
10	100	2	$2.48238070579414 \times 10^{-3}$	$2.48238070579414 \times 10^{-3}$
10	100	100	$2.43753901374804 \times 10^{-2}$	$2.43753901374804 \times 10^{-2}$
5	5	5	0.190983005625053	0.190983005625053
5	5	4	0.175211835787862	0.175211835787862

Table 2. Geometrical efficiency ε_g for a circular detector of radius R and a linear source of length 2a. The source and detector axes are parallel and separated by a lateral distance ρ . The center of the source is an axial distance h from the detector plane. Distances are in arbitrary units.

R	ρ	h	a	Geometrical efficiency (ε_g)	
				Conway [1]	Present work
10	1	6	1	0.2424075268155220	0.2424075268155218
10	1	6	2	0.2444939236648650	0.2444939236648647
10	1	6	3	0.2479120907431220	0.2479120907431219
10	1	6	4	0.2525702335275070	0.2525702335275068
10	1	6	5	0.2583365907829720	0.2583365907829719
10	1	6	6	0.2650417921134300	0.2650417921134298
20	1	6	6	0.3613152934378430	0.3613152934378427
50	1	6	6	0.4408231864430030	0.4408231864430028
10^2	1	6	6	0.4701050189567020	0.4701050189567020
10^3	1	6	6	0.4970001057426270	0.4970001057426270
10^6	1	6	6	0.4999970000000000	0.4999970000000000
5	1	5	4	0.1726042018147730	0.1726042018147727
5	2	5	4	0.1645441216554290	0.1645441216554288
5	3	5	4	0.1502632976034040	0.1502632976034037
5	4	5	4	0.1283998422373930	0.1283998422373929
5	5	5	4	0.0988096991450620	0.0988096991450618
5	6	5	4	0.0706900253117640	0.0706900253117636
5	7	5	4	0.0512352434451088	0.0512352434451085
5	8	5	4	0.0381704509705044	0.0381704509705041
5	9	5	4	0.0291077849249144	0.0291077849249142
5	10	5	4	0.0226308012432528	0.0226308012432526
20	5	1	1	0.4738338789017140	0.4738338789017137
20	5	2	1	0.4479010451301750	0.4479010451301748
20	5	3	1	0.4224234986937620	0.4224234986937619
20	5	4	1	0.3976019974352420	0.3976019974352418
20	5	5	1	0.3736084804781520	0.3736084804781518
20	5	10	1	0.2697132766757590	0.2697132766757587
20	5	20	1	0.1424329648079320	0.1424329648079317
20	5	40	1	0.0519778159212070	0.0519778159212052

4 Conclusions

In this paper, it becomes easier using a compact mathematical expression to calculate the geometrical efficiency of a circular detector of radius R and a line source located along and parallel to the axis of a circular detector. The agreement between the results calculated in this work and the published values is excellent; the percentage deviation was vanished (0.00%). This means that the present approach is efficient and sufficiently powerful to evaluate the geometrical efficiency of circular detectors.

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